

Evaluation of Two-Stage Soft-Switched Flyback Micro-inverter for Photovoltaic Applications

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Abstract

The research on the micro inverters for photovoltaic (PV) applications has been increased in recent years due to its advantages of minimization of module mismatch losses, the elimination of serial diode losses, and suitability for mass production etc. However, the micro-inverters suffer from the low voltage at the input PV terminals that causes high conduction loss and requires large electrolytic capacitors for decoupling purposes. The electrolytic capacitors have relatively low lifetime in comparison with the PV modules, and restricts the micro-inverter service life significantly. Moreover, the high conduction loss decreases the micro-inverters conversion efficiency considerably. In order to mitigate these drawbacks, two stage micro-inverters are generally proposed. In this study, a 200 W two stage soft switched flyback micro-inverter is designed for highest efficiency, and compared with the conventional single stage flyback micro-inverter. By using two-stage soft-switched flyback micro-inverter, the decoupling capacitor value is decreased by 10 times, and maximum efficiency is increased by 13.7%. The experimental results are also presented.

1. Introduction

The installed solar PV capacity is growing faster than other renewable technologies during the period from end-2006 through 2011 with increasing an average of %58 annually [1]. PV power installation trend is large-scale ground-mounted system, but rooftop small scale systems play also an important role. PV systems can be classified into two categories; stand-alone and grid connected. Due to intermittent characteristic of solar irradiation, large scale batteries are required in stand-alone PV systems. On the other hand, the grid connected PV systems use the utility grid as an infinite storage element, and hence, eliminate the batteries which have high cost and low life time [2].

Grid-tied PV systems are connected to the utility grid through an inverter. Central and string type inverters operate at a single common operating point for all PV modules attached to the inverter, and hence mismatching or partially shading of PV modules create considerable MPP losses. In micro-inverter technology, each PV module has their own DC-AC inverter, and therefore can be operated at its own maximum power point (MPPT) [3].

Micro-inverters can be designed as single stage or two stages for single phase utility connection [4], where the maximum instantaneous power injected to the grid is twice of the PV module average power. Therefore, a power decoupling circuit is necessary in order to obtain instantaneous power balance. Capacitors as an energy reservoir are used simply for power

decoupling purposes [5]. However, decoupling capacitor value at low voltage level may become very large when total harmonic distortion (THD) and PV utilization ratio are taken into account [6]. Electrolytic capacitors are usually used in the decoupling circuits due to advantages of low cost and high capacitance. Unfortunately, it has very low life time when compared to the PV modules (>20 years), and therefore not suitable for using in micro-inverter circuits when considering lifetime.

Although single stage micro-inverters have simple structure and easy control, it suffers from the low input PV voltage. The power decoupling circuits working at low voltage requires usually electrolytic capacitors. Additionally the conduction losses increase at low voltage/high current conditions. As an alternative, in two stage micro-inverters, the PV voltage is boosted at the first stage and the power decoupling function is realized at high voltage side which reduces the decoupling capacitor value considerably. Thus the film capacitors can be used and the micro-inverter life time is lengthened. On the other hand, having two power conversion stages may reduce the overall conversion efficiency significantly, but soft switching techniques can mitigate this problem [7]. Despite its several advantageous, two stage topologies have complicated structure, high cost and difficult to control.

In the literature, micro-inverters are well reviewed [8–10] and the flyback based topology is the most attractive one because of simple current control, low part counts and potentially low cost. Flyback type micro-inverters have three operating modes; such as discontinuous (DCM), continuous (CCM) and boundary conduction modes (BCM) [10-11]. Since the injected current into the grid can be modulated by open loop control without current sensor, the DCM operation is usually preferred.

In order to amplify the PV voltage in the first stage, many candidate soft switched converters were proposed in the literature [13–16]. These are mainly classified as isolated, non-isolated DC/DC PWM converters and resonant converters. Since the second stage isolates the PV module from the grid, non-isolated converters can be used for efficiency consideration. Furthermore, the isolated DC/DC PWM converters can be preferred where high voltage gain is required. On the other hand, resonant converters may not operate efficiently under wide load range such as PV power whose power ranges from zero to rated power during the day.

In this study, a two-stage soft-switched flyback micro-inverter is designed and compared with a conventional counterpart. In the first and second stages, a single-switch soft-switched boost DC/DC converter and DCM soft-switched flyback inverter are implemented respectively [16-17]. This paper is organized as follows; the analysis of conventional DCM flyback micro-inverter and two-stage soft-switched flyback micro-inverter are given in the sections 2 and 3, respectively. The experimental results are presented in the section 4.

2. Conventional DCM Flyback Micro-inverter

Conventional DCM flyback micro-inverter topology is given in Fig. 1. The main switch S1 is turned on for the duration of t_{on} , and a certain amount of energy is stored in magnetizing inductance L_m . The stored energy is transferred to the secondary side by turning off the S1 during t_{off} time through the switches S2-D1 or S3-D2 (depending on the grid voltage positive or negative cycle). For DCM operation, the total time ($t_{on}+t_{off}$) must be shorter than switching frequency period T_s . By using this property, the maximum duty ratio $d_p (=t_{on}/T_s)$ can be expressed as [10];

$$d_p = \frac{1}{1 + (V_{dc} / nV_{gm})} \quad (1)$$

where V_{dc} is the input PV MPPT voltage, V_{gm} is the maximum grid voltage and n is the transformer turn ratio.

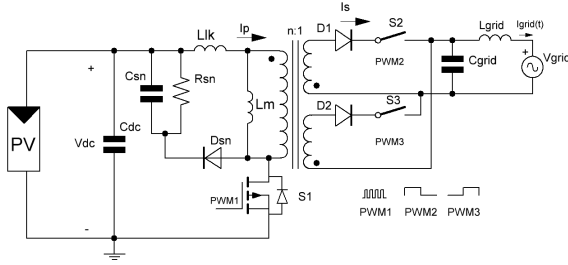


Fig. 1. Conventional DCM Flyback Topology

Despite the main switch S_1 turns on softly with zero current, it has considerable switching loss at turn-off. On the other hand, the drain voltage of the mosfet is clamped by the RCD snubber circuit ($R_{sn}-C_{sn}-D_{sn}$) [12], and therefore the leakage inductance energy which can be assumed as 2.5% of the energy stored in L_m [18], is dissipated in the snubber resistor R_{sn} . Moreover the conduction loss on the main switch is high, since the rms value of I_p is relatively large due to low input dc voltage. The rms input current can be written as follows [10], [18];

$$I_{p,rms} = \sqrt{\frac{64}{9\pi} \frac{P^2}{d_p^2 V_{dc}^2}} \quad (2)$$

where P is the maximum PV power. It should be noted that, $I_{p,rms}$ depends inversely on the V_{dc} . Hence, if the input DC voltage increases, $I_{p,rms}$ decreases and the conduction loss in the primary circuit reduces significantly.

On the other hand, the decoupling capacitor value can be calculated by [5];

$$C_{dc} = \frac{P}{2\pi V_{dc} f_{grid} \Delta V_{dc}} \quad (3)$$

where f_{grid} is the grid frequency and ΔV_{dc} is peak-to-peak DC bus ripple voltage. Instantaneous input power and the DC bus voltage are depicted in Fig. 2.

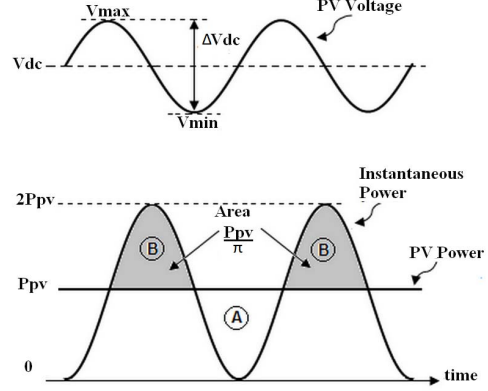


Fig. 2. DC bus voltage and instantaneous input power

The switching frequency harmonics on the output current I_{grid} are filtered by the output filter $C_{grid}-L_{grid}$. However, the low frequency harmonics that are created by the DC-bus voltage ripple are not filtered by the output filter [6]. In order to keep these harmonics at low level, we proposed the voltage ripple ΔV_{dc} as 5% by taking into consideration the THD and PV utilization ratio [6]. Consequently, all parameters used in the analysis of conventional DCM flyback circuit are listed in Table 1.

Table 1. Conventional DCM Flyback Micro-inverter Parameter Values

Parameter	Value	Parameter	Value
n	0.1428	C_{grid}	0.33 μ F
d_p	0.55	R_{sn}	1.67 k Ω
L_m	6.64 μ H	C_{sn}	100 nF
L_{lk}	0.2 μ H	C_{dc}	6 mF
L_{grid}	1.75 mH	$f_{s,f}$	75 KHz

3. Two-Stage Soft-Switched Flyback Micro-inverter

The block diagram of a two-stage flyback micro-inverter is shown in Fig. 3. In this topology, both the MPPT and PV voltage amplification tasks are achieved in the first stage and DC/AC inversion is realized in the second stage. In this study, the intermediate DC-bus voltage is selected as 110 V, and also soft switching techniques are employed in both stages.

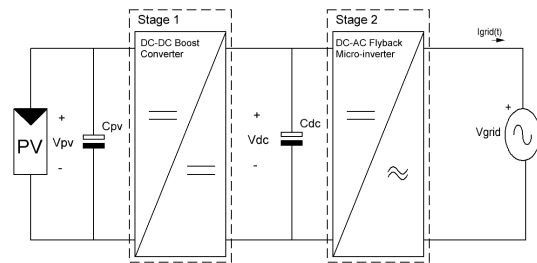


Fig. 3. The Block Diagram of Two-stage Flyback Micro-inverter

3.1. The Soft-switched DC/DC Boost Converter

The DC/DC boost converter shown in Fig. 4 is selected for the first stage because of the features such that single switch, easy to control, high efficiency and soft switching [16]. This converter has two coupled inductors and a resonance capacitor to implement the soft switching.

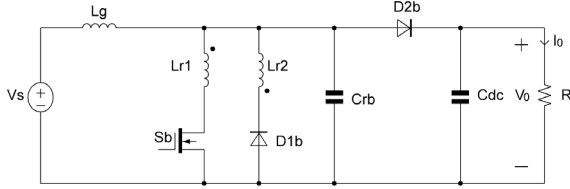


Fig. 4. Soft-Single-Switched Boost Converter

The soft switching operation of the converter is briefly as follows: Before turn on the switch S_b , the current in the inductors L_{r1} and L_{r2} are zero, the diode D_{2b} current is equal to output current I_0 , and C_{rb} capacitor voltage is equal to the output voltage V_0 in steady state. When the switch S_b is turned on, the switch current increases linearly due to series inductor L_{r1} and soft turn on occurs at zero current. When the switch current reaches to I_0 , the current in diode D_{2b} becomes zero and it is turned off at zero current. From this moment, C_{rb} and L_{r1} start to resonance and L_{r1} gets all the energy of C_{rb} , and then the voltage of capacitor C_{rb} reduces to zero. Later, the diode D_{1b} turns on under zero voltage and small circulating current flows through coupled inductors during the switch S_b on-time. Due to zero voltage at capacitor C_{rb} , the switch S_b is turned off at zero voltage, and the current in L_{r1} inductor is transferred to L_{r2} , and the capacitor C_{rb} starts to charge. In order to guarantee the soft switching operation, the minimum values for resonant elements L_{r1} and C_{rb} can be expressed as [16];

$$C_{rb} > C_{rb,\min} = \frac{I_{sw} t_{k,s}}{2V_{sw}} \quad (4)$$

$$L_{r1} > L_{r1,\min} = \frac{V_{sw} t_{a,s}}{I_{sw}}$$

where I_{sw} is the current of switch S_b before turn off, $t_{k,s}$ is the switch current fall time, V_{sw} is the voltage of switch S_b after turn off, and $t_{a,s}$ is the switch current rise time.

The filter element L_g can be designed as in the case of conventional boost converter. Since the C_{dc} is the DC-bus capacitor of second stage, it acts as decoupling capacitor, and therefore should be sized according to (3). The parameters of the designed circuit are listed in Table 2.

Table 2. Parameters of the Boost Converter

Parameter	Value	Parameter	Value
L_{r1}	15 uH	L_g	130 uH
L_{r2}	112 uH	C_{dc}	600 uF
C_{rb}	10 nF	$f_{s,b}$	100 kHz

3.2. The Soft-switched DCM Flyback Micro-inverter

The soft-switched DCM flyback topology employed in the second stage of the micro-inverter is given in Fig. 5 [17]. In this

topology, an auxiliary circuit composed of D_{a1} , D_{a2} , L_r , C_r and S_a is added to conventional DCM flyback micro-inverter in order to obtain soft switching and active-clamp operations. The energy stored in the leakage inductance is transferred back to the DC bus and the overall efficiency is improved.

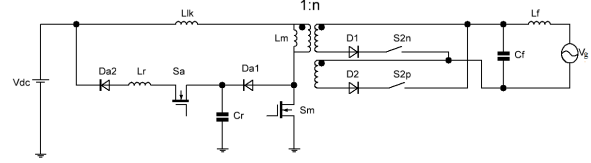


Fig. 5. Soft Switched DCM Flyback Micro-inverter

The soft switching operation of the converter is briefly as follows: S_m and S_a switches turn on and off together. Before turn on the switches, the inductors L_m and L_r have zero current; therefore soft turn-on is obtained at zero current for both switches. The switch S_m turns off softly at zero voltage due to parallel capacitor C_r . Since the current through the switch S_a is zero at this moment, the switch S_a is also turned off at zero current [19]. All diodes and switches are soft-switched in this topology, and the leakage inductance energy is recycled. Hence, high switching frequency can be chosen, and thus, efficiency improvement can be obtained. L_m , n , L_f and C_f are selected as in the conventional flyback inverter [10]. The resonant elements L_r and C_r values should be selected by using (4) as mentioned before. The parameters of the designed circuit are listed in Table 3.

Table 3. Parameters of the Soft-switched DCM Flyback Micro-inverter

Parameter	Value	Parameter	Value
n	3	C_r	10 nF
d_p	0,5	L_f	1,75 mH
L_m	57 uH	C_f	0,33 uF
L_{lk}	0,75 uH	C_{dc}	600 uF
L_r	24 uH	$f_{s,f}$	75 KHz

4. Experimental Results

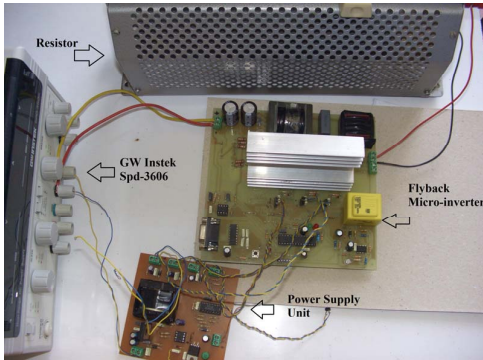
The prototypes of single-stage conventional DCM flyback micro-inverter and two-stage soft-switched DCM flyback micro-inverter were realized as shown in Fig. 6 (a) and (b) respectively. The input power to micro-inverter was taken from the laboratory DC power supply (GW Instek Spd-3606).

DC bus voltage of the two stage micro-inverter and the output voltage of micro-inverter are shown in Fig. 8 while 377Ω resistor is used as a load. It can be seen from the figure that, the frequency of DC bus voltage variation is twice of the frequency of the output voltage, and the average DC bus voltage is equal to 110V as expected.

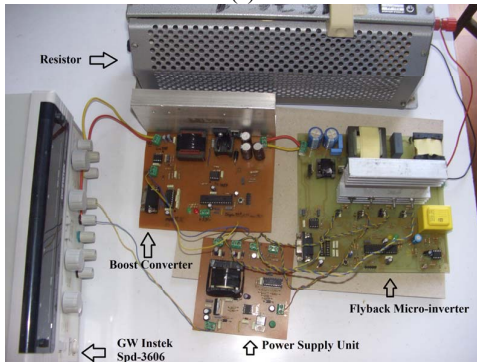
The soft switching operations are verified for the two-stage micro-inverter as shown in the figures 9-12. The boost converter's main switch (S_b) turn on and turn off waveforms can be seen in Fig. 9 and Fig. 10 respectively. Turn on occurs at zero current and turn off occurs at zero voltage. The soft switched flyback inverter's main switch (S_m) turn on and turn off waveforms can be seen in Fig. 11. Similarly, the switch turns on at zero current and turn off at zero voltage. Turn on and off characteristics of auxiliary switch (S_a) are given in Fig.12 where the switch turns on and off at zero current.

The efficiency curve with respect to the input power for both topologies were measured and are shown Fig. 7. At 145 W input power, while the efficiency for the conventional DCM flyback micro-inverter is 78%, it is 88.7% for the two-stage soft-switched DCM flyback micro-inverter. The European efficiency [18] is improved from 83.3% to 86.8% as expected.

For 7% DC bus voltage ripple ($=\Delta V_{dc}/V_{dc} * 100\%$), required capacitor capacity is calculated and used as 6000 uF and 600 uF for conventional and two-stage soft-switched flyback micro-inverter respectively. When 377 Ω resistor is used as load, THD of the injected current is 3.5% for the both inverters as expected from [6].



(a)



(b)

Fig. 6. (a) Conventional Flyback Micro-inverter (b) Two-stage Soft-Switched Flyback Micro-inverter

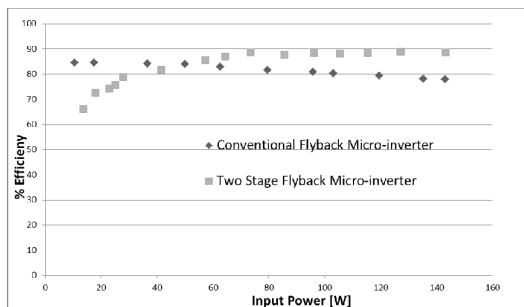


Fig. 7. Efficiency Measurement of Conventional and Two-stage Soft-switched DCM Flyback Micro-inverters

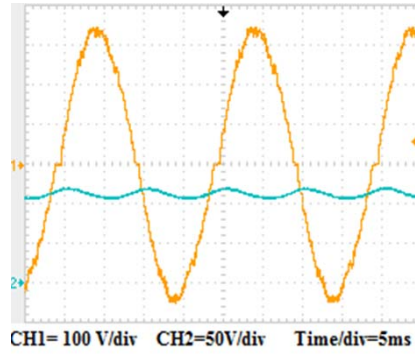


Fig. 8. DC Bus Voltage Variation and Output Voltage through 377 Ω resistor

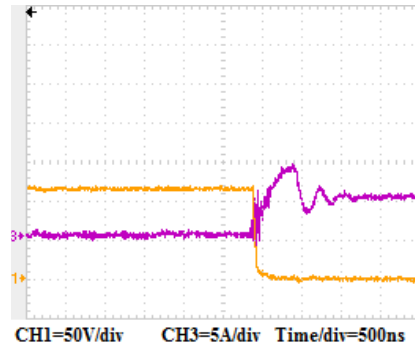


Fig. 9. The S_b switch's turn on time

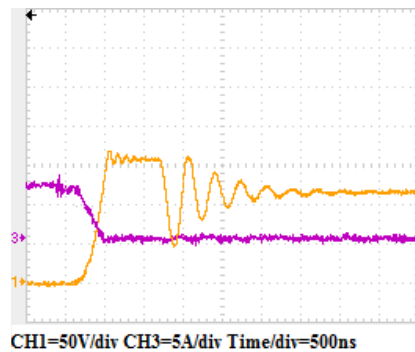


Fig. 10. The S_b switch's turn off time

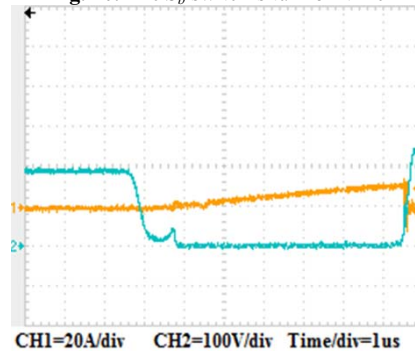


Fig. 11. The S_m switch's turn on and turn off times

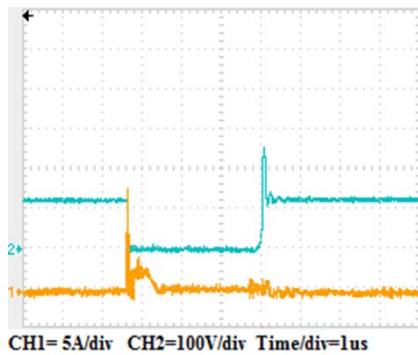


Fig. 12. The S_a switch's turn on and turn off times

5. Conclusion

Single-stage conventional DCM flyback micro-inverter and two-stage soft-switched DCM flyback micro-inverter were analyzed and experimentally compared. By boosting the input DC voltage, decoupling capacitor value reduced from 6000 μF to 600 μF , and efficiency is increased from 78% to 88.7%. Moreover, decreasing the decoupling capacitor value can lead to change electrolytic capacitors with film types which extends the inverter life time further. However, two-stage soft switched flyback micro-inverter brings extra switching elements and passive components. As a result of this, cost and control complexity increase.

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